

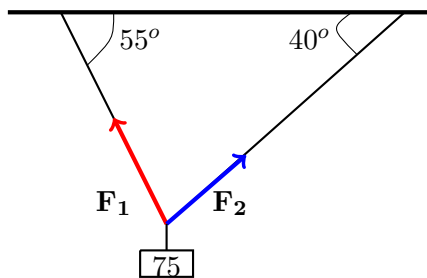
Applications of Vectors

1. **Velocity and Speed.** The magnitude of a velocity vector is called speed.

Example: A quarterback throws a football with an angle of elevation 60° and speed 50 ft/s. Find the horizontal and vertical components of the velocity vector.

2. **Force.** A force is represented by a vector because it has both magnitude and a direction. If several forces are acting on an object, the **resultant force** experienced by the object is the vector sum of these forces.

Example: A 75-N weight is suspended by two wires, as shown below. Find the forces \mathbf{F}_1 and \mathbf{F}_2 acting in both wires.



DNP

Note: The resultant $\mathbf{F}_1 + \mathbf{F}_2$ counterbalances the weight $\mathbf{w} = \langle 0, -75 \rangle$.

We have $\mathbf{F}_1 + \mathbf{F}_2 = -\mathbf{w}$

$$\langle -|F_1|\cos(55^\circ), |F_1|\sin(55^\circ) \rangle + \langle |F_2|\cos(40^\circ), |F_2|\sin(40^\circ) \rangle = -\langle 0, -75 \rangle$$

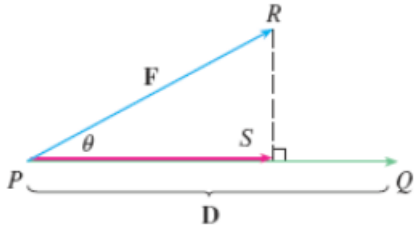
$$\begin{cases} -|F_1|\cos(55^\circ) + |F_2|\cos(40^\circ) = 0 & \rightarrow |F_2| = \frac{|F_1|\cos(55^\circ)}{\cos(40^\circ)} \\ |F_1|\sin(55^\circ) + |F_2|\sin(40^\circ) = 75 \end{cases}$$

$$\text{then } |F_1|\sin(55^\circ) + \frac{|F_1|\cos(55^\circ)}{\cos(40^\circ)}\sin(40^\circ) = 75$$

$$\Rightarrow |F_1| = \frac{75}{\sin(55^\circ) + \frac{\cos(55^\circ)\sin(40^\circ)}{\cos(40^\circ)}} = ?$$

DNP

3. **Work.** Suppose the force is a vector $\mathbf{F} = \overrightarrow{PR}$ pointing in some direction, as below. If the force moves the object from P to Q , then the *displacement vector* is $\mathbf{D} = \overrightarrow{PQ}$.



The **work** done by this force is defined to be the product of the component of the force along \mathbf{D} and the distance moved:

$$\mathbf{W} = |\mathbf{F}||\mathbf{D}| \cos(\theta) = \mathbf{F} \cdot \mathbf{D}$$

Example: A sled is pulled along a level path through snow by a rope. A 25-lb force acting at an angle of 45° above the horizontal moves the sled 60 ft. Find the work done by the force.

$$|\mathbf{F}| = 25 \text{ lb}$$

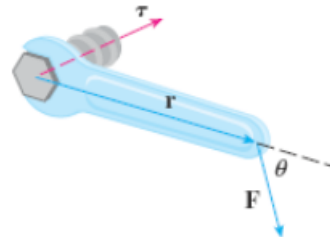
$$\theta = 45^\circ$$

$$|\mathbf{D}| = 60 \text{ ft}$$

$$W = |\mathbf{F}||\mathbf{D}| \cos \theta \Rightarrow (25)(60) \frac{\sqrt{2}}{2} = \underline{750\sqrt{2} \text{ ft}\cdot\text{lb}}$$

4. **Torque.** The **torque** τ (relative to the origin) is defined to be the cross product of the position and force vectors, and measures the tendency of the body to rotate about the origin.

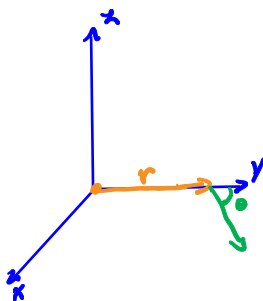
$$\tau = \mathbf{r} \times \mathbf{F}$$



The magnitude of the torque vector is

$$|\tau| = |\mathbf{r} \times \mathbf{F}| = |\mathbf{r}||\mathbf{F}| \sin(\theta)$$

Example: A wrench 30cm long lies along the positive y -axis and grips a bolt at the origin. A force is applied in the direction $\langle 0, 3, -4 \rangle$ at the end of the wrench. Find the magnitude of the force needed to supply 100N·m of torque to the bolt.



$$\|\mathbf{r}\| = 30 \text{ cm} = 0.3 \text{ m}$$

$$\mathbf{F} = \lambda \langle 0, 3, -4 \rangle \quad \text{Goal: } |\mathbf{F}| = \lambda(5) = ?$$

$$\|\tau\| = 100$$

Note that $|\tau| = \underbrace{\|\mathbf{r}\|}_{0.3} \underbrace{\|\mathbf{F}\|}_{5\lambda} \sin \theta$

$$100 = (0.3)(5\lambda) \frac{4}{5} \Rightarrow 5\lambda = \frac{5(100)}{4(0.3)}$$

so, magnitude of the force is $|\mathbf{F}| = 5\lambda = \frac{5(100)}{4(0.3)}$